

# Physics 371 HW #9

## Solutions

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$$1) \quad L_x = \frac{1}{2} (L_+ + L_-)$$

$$L_y = \frac{1}{2i} (L_+ - L_-)$$

$$\langle \ell m | L_{\pm} | \ell m \rangle = 0 \Rightarrow \langle L_x \rangle = \langle L_y \rangle = 0$$

$$\langle L_x^2 \rangle = \frac{1}{4} \langle \underbrace{L_+^2}_0 + \underbrace{L_-^2}_0 + L_+ L_- + L_- L_+ \rangle$$

$$= \frac{1}{2} \langle L^2 - L_z^2 \rangle = \frac{\hbar^2}{2} [\ell(\ell+1) - m^2]$$

$$\langle L_y^2 \rangle = -\frac{1}{4} \langle \underbrace{L_+^2}_0 + \underbrace{L_-^2}_0 - L_+ L_- - L_- L_+ \rangle$$

$$= \frac{1}{4} \langle L_+ L_- + L_- L_+ \rangle = \frac{\hbar^2}{2} [\ell(\ell+1) - m^2]$$

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$$2) \quad \Delta L_x^2 = \langle L_x^2 \rangle - \langle L_x \rangle^2 = \frac{\hbar^2}{2} [\ell(\ell+1) - m^2]$$

$$\Delta L_y^2 = \langle L_y^2 \rangle - \langle L_y \rangle^2 = \frac{\hbar^2}{2} [\ell(\ell+1) - m^2]$$

$$\Delta L_x \Delta L_y = \frac{\hbar^2}{2} [\ell(\ell+1) - m^2] \quad \boxed{2}$$

$$\frac{\hbar}{2} |\langle L_z \rangle| = \frac{\hbar^2}{2} |m|$$

$$\frac{\hbar^2}{2} [\ell(\ell+1) - m^2] \stackrel{?}{\geq} \frac{\hbar^2}{2} |m|$$

$$\ell(\ell+1) - m^2 \geq |m| \quad ?$$

$$\ell(\ell+1) - m^2 \geq \ell(\ell+1) - \ell^2 = \ell \geq |m| \quad \checkmark$$

Equality holds for  $m = \pm \ell$ .

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$$3) \quad 6\hbar^2 = \hbar^2 \ell(\ell+1) \quad \Rightarrow \quad \ell = 2$$

$$\Rightarrow \quad L_y = 0, \pm \hbar, \pm 2\hbar$$

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$$4) \quad \hat{L}_x \Psi = \lambda_x \Psi \quad \hat{L}_y \Psi = \lambda_y \Psi$$

$$[\hat{L}_x, \hat{L}_y] \Psi = i\hbar L_z \Psi$$

$$(\lambda_x \lambda_y - \lambda_y \lambda_x) \Psi = i\hbar L_z \Psi$$

$$0 = L_z \Psi$$

$$[\hat{L}_z, \hat{L}_x] \Psi = i\hbar \hat{L}_y \Psi = i\hbar \lambda_y \Psi \quad \boxed{3}$$

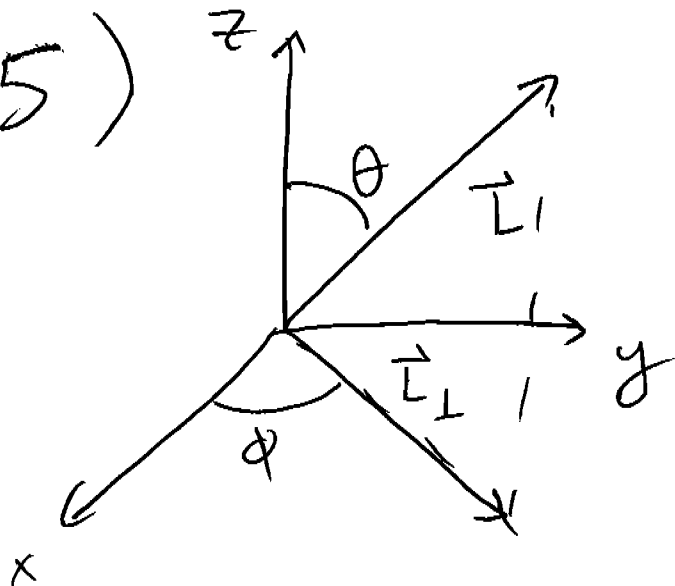
$$\hat{L}_z \lambda_x \Psi - 0 = i\hbar \lambda_y \Psi$$

$$0 = \lambda_y \Psi$$

$$[\hat{L}_y, \hat{L}_z] \Psi = i\hbar \hat{L}_x \Psi$$

$$0 = \lambda_x \Psi \Rightarrow \lambda_x = \lambda_y = \lambda_z = 0$$

5)



$$\tan \theta = \frac{|\vec{L}_\perp|}{|L_z|}$$

$$\begin{aligned} \vec{L}_\perp^2 &= \vec{L}^2 - L_z^2 \\ &= \hbar^2 [l(l+1) - m^2] \end{aligned}$$

$$\frac{|\vec{L}_\perp|}{|L_z|} = \sqrt{\frac{l(l+1) - m^2}{m^2}} = \sqrt{\frac{l(l+1)}{m^2} - 1}$$

$$\tan \theta \geq \sqrt{\frac{l(l+1)}{l^2} - 1} = \sqrt{\frac{1}{l}} \quad \text{Q.E.D.}$$

6) Griffiths 4.1

(a)  $[x, y] = xy - yx = 0$ , etc., so  $[r_i, r_j] = 0$ .

$$[p_x, p_y] f = -\hbar^2 \left( \frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right) = 0, \text{ etc.}$$

so  $[p_i, p_j] = 0$ .

$$[x, p_x] = i\hbar = [y, p_y] = [z, p_z], \text{ but}$$

$$[x, p_y] f = -i\hbar \left( x \frac{\partial f}{\partial y} - \frac{\partial}{\partial y} (x f) \right) = 0, \text{ etc.}$$

so  $[r_i, p_j] = i\hbar \delta_{ij}$ .

(b)  $\frac{d}{dt} \langle \vec{r} \rangle = \frac{1}{i\hbar} \langle [\vec{r}, \hat{H}] \rangle = \frac{1}{2i\hbar m} \langle [\vec{r}, \vec{p}^2] \rangle$

$$[x, \vec{p}^2] = 2i\hbar p_x, \text{ etc., so } [\vec{r}, \vec{p}^2] = 2i\hbar \vec{p}$$

$$\frac{d}{dt} \langle \vec{r} \rangle = \frac{1}{m} \langle \vec{p} \rangle$$

$$\frac{d}{dt} \langle \vec{p} \rangle = \frac{1}{i\hbar} \langle [\vec{p}, \hat{H}] \rangle = \frac{1}{i\hbar} \langle [\vec{p}, V(\vec{r})] \rangle$$

$$[\vec{p}, V(\vec{r})] f(\vec{r}) = \frac{\hbar}{i} \nabla(Vf) - \frac{\hbar}{i} V \nabla f$$

$$= (-i\hbar \nabla V) f$$

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$$\Rightarrow [\vec{p}, V(\vec{r})] = -i\hbar \nabla V$$

$$\frac{d}{dt} \langle \vec{p} \rangle = \langle -\nabla V \rangle$$

$$(c) \Delta r_i \Delta p_j \geq \frac{1}{2} |\langle [r_i, p_j] \rangle| = \frac{\hbar}{2} \delta_{ij}$$

7) Griffiths 4.19

$$L_x = y p_z - z p_y$$

$$L_y = z p_x - x p_z$$

$$L_z = x p_y - y p_x$$

(a)  $[L_z, x]$

||

$$[x p_y - y p_x, x] = -y [p_x, x]$$

$$= i\hbar y \checkmark$$

$$[L_z, y] = [x p_y - y p_x, y] = x [p_y, y] = -i\hbar x \checkmark$$

$$[L_z, z] = [x p_y - y p_x, z] = 0 \checkmark$$

$$[L_z, p_x] = [x p_y - y p_x, p_x] = [x, p_x] p_y = i\hbar p_y \checkmark$$

$$[L_z, p_y] = [x p_y - y p_x, p_y] = -[y, p_y] p_x = -i\hbar p_x \quad (6)$$

$$[L_z, p_z] = [x p_y - y p_x, p_z] = 0 \quad \checkmark$$

$$\begin{aligned} (b) \quad [L_z, L_x] &= [x p_y - y p_x, y p_z - z p_y] \\ &= [x p_y, y p_z] + [y p_x, z p_y] \\ &= x [p_y, y] p_z + z [y, p_y] p_x \\ &= -i\hbar x p_z + i\hbar z p_x = i\hbar (z p_x - x p_z) \\ &= i\hbar L_y \quad \checkmark \end{aligned}$$

$$\begin{aligned} (c) \quad [L_z, r^2] &= [L_z, x^2] + [L_z, y^2] + 0 \\ &= x [L_z, x] + [L_z, x] x + y [L_z, y] + [L_z, y] y \\ &= 2i\hbar xy - 2i\hbar xy = 0 \end{aligned}$$

$$\begin{aligned} [L_z, p^2] &= [L_z, p_x^2] + [L_z, p_y^2] \\ &= 2i\hbar p_x p_y - 2i\hbar p_x p_y = 0 \end{aligned}$$

$$(d) \quad [\vec{L}, \hat{H}] = \underbrace{[\vec{L}, p^2]}_0 \frac{1}{2m} + [\vec{L}, V(r)]$$

$$[L_x, V(r)] = [yP_z - zP_y, V(r)]$$

$$= y[P_z, V(r)] - z[P_y, V(r)]$$

$$[P_z, V(r)]f(\vec{r}) = \left(\frac{\hbar}{i} \frac{\partial V}{\partial z}\right) f(\vec{r})$$

$$[P_y, V(r)] = \frac{\hbar}{i} \frac{\partial V}{\partial y}$$

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$r^2 = x^2 + y^2 + z^2$$

$$2rdr = 2x dx + 2y dy + 2z dz$$

$$\frac{\partial}{\partial y} V(r) = \frac{\partial V}{\partial r} \frac{\partial r}{\partial y} = \frac{y}{r} \frac{dV}{dr}$$

$$\frac{\partial}{\partial z} V(r) = \frac{z}{r} \frac{dV}{dr}$$

$$\Rightarrow [L_x, V(r)] = \frac{\hbar}{i} \frac{yz}{r} \frac{dV}{dr} - \frac{\hbar}{i} \frac{zy}{r} \frac{dV}{dr} = 0$$

similarly,  $[L_y, V(r)] = 0$ ,  $[L_z, V(r)] = 0$ .

$$\Rightarrow \left[ \vec{L}, \frac{\vec{p}^2}{2m} + V(r) \right] = 0$$

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8) Griffiths 4.21

$$(a) L_+ L_- f = -\hbar^2 e^{i\phi} \left( \frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) \left[ e^{-i\phi} \left( \frac{\partial f}{\partial \theta} - i \cot \theta \frac{\partial f}{\partial \phi} \right) \right]$$

$$= -\hbar^2 e^{i\phi} \left\{ e^{-i\phi} \left[ \frac{\partial^2 f}{\partial \theta^2} - i \left( -\csc^2 \theta \frac{\partial f}{\partial \phi} + \cot \theta \frac{\partial^2 f}{\partial \theta \partial \phi} \right) \right] \right.$$

$$+ i \cot \theta \left[ -i e^{-i\phi} \left( \frac{\partial f}{\partial \theta} - i \cot \theta \frac{\partial f}{\partial \phi} \right) \right.$$

$$\left. \left. + e^{-i\phi} \left( \frac{\partial^2 f}{\partial \phi \partial \theta} - i \cot \theta \frac{\partial^2 f}{\partial \phi^2} \right) \right] \right\}$$

$$= -\hbar^2 \left( \frac{\partial^2 f}{\partial \theta^2} + i \csc^2 \theta \frac{\partial f}{\partial \phi} - i \cot \theta \frac{\partial^2 f}{\partial \theta \partial \phi} \right.$$

$$+ \cot \theta \frac{\partial f}{\partial \theta} - i \cot^2 \theta \frac{\partial f}{\partial \phi} + i \cot \theta \frac{\partial^2 f}{\partial \phi \partial \theta} \left.$$

$$\left. + \cot^2 \theta \frac{\partial^2 f}{\partial \phi^2} \right)$$

$$= -\hbar^2 \left[ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} \right.$$

$$\left. + i (\csc^2 \theta - \cot^2 \theta) \frac{\partial}{\partial \phi} \right] f$$

$$\text{So } L_+ L_- = -\hbar^2 \left( \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right)$$

Q.E.D



$$(b) \quad L_z = \frac{\hbar}{i} \frac{\partial}{\partial \phi}, \quad \vec{L}^2 = L_+ L_- + L_z^2 - \hbar L_z, \quad (9)$$

$$\text{so } \vec{L}^2 = -\hbar^2 \left( \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \cot^2 \theta \frac{\partial^2}{\partial \phi^2} + i \frac{\partial}{\partial \phi} \right)$$

$$- \hbar^2 \frac{\partial^2}{\partial \phi^2} - \hbar \left( \frac{\hbar}{i} \right) \frac{\partial}{\partial \phi}$$

$$= -\hbar^2 \left( \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right)$$

$$= -\hbar^2 \left[ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right]$$

Q.E.D.