

1) a) Momentum representation:

$$\vec{r} = i\hbar \frac{\partial}{\partial \vec{p}}$$

$$\begin{aligned} [\vec{r}, \hat{T}(\vec{a})] \tilde{\Psi}(\vec{p}) &= i\hbar \left(\frac{\partial}{\partial \vec{p}} [\hat{T}(\vec{a}) \tilde{\Psi}(\vec{p})] - \hat{T}(\vec{a}) \frac{\partial \tilde{\Psi}}{\partial \vec{p}} \right) \\ &= i\hbar \frac{\partial \hat{T}(\vec{a})}{\partial \vec{p}} \tilde{\Psi}(\vec{p}) \end{aligned}$$

$$\Rightarrow [\vec{r}, \hat{T}(\vec{a})] = i\hbar \frac{\partial \hat{T}(\vec{a})}{\partial \vec{p}} = -\vec{a} \hat{T}(\vec{a})$$

$$\begin{aligned} b) \vec{r} \hat{T}(\vec{a}) |\vec{r}_0\rangle &= \hat{T}(\vec{a}) \vec{r} |\vec{r}_0\rangle - \vec{a} \hat{T}(\vec{a}) |\vec{r}_0\rangle \\ &= (\vec{r}_0 - \vec{a}) \hat{T}(\vec{a}) |\vec{r}_0\rangle \end{aligned}$$

Position eigenstate with eigenvalue

$$\vec{r}_0 - \vec{a}.$$

$$2) i\hbar \frac{da}{dt} = [a, H] = \hbar\omega [a, a^\dagger a]$$

$$a) = \hbar\omega [a, a^\dagger] a = \hbar\omega a$$

$$\frac{da}{dt} = -i\omega a \Rightarrow \boxed{a(t) = a(0) e^{-i\omega t}}$$

$$\begin{aligned} i\hbar \frac{da^\dagger}{dt} &= [a^\dagger, H] = \hbar\omega [a^\dagger, a^\dagger a] = \hbar\omega a^\dagger [a^\dagger, a] \\ &= -\hbar\omega a^\dagger \end{aligned}$$

$$\frac{da^\dagger}{dt} = i\omega a^\dagger \Rightarrow \boxed{a^\dagger(t) = a^\dagger(0) e^{i\omega t}}$$

$$2) b) \quad \hat{X}(t) = \sqrt{\frac{\hbar}{2m\omega}} (a^\dagger(t) + a(t))$$

$$\hat{P}_x(t) = i \sqrt{\frac{m\hbar\omega}{2}} (a^\dagger(t) - a(t))$$

$$\begin{aligned} \langle X(t) \rangle &= (\alpha^* \langle 0| + \beta^* \langle 1|) a^\dagger(t) + a(t) (\alpha | 0\rangle + \beta | 1\rangle) \sqrt{\frac{\hbar}{2m\omega}} \\ &= (\beta^* \alpha \langle 1| a^\dagger e^{i\omega t} | 0\rangle + \alpha^* \beta \langle 0| a e^{-i\omega t} | 1\rangle) \sqrt{\frac{\hbar}{2m\omega}} \\ &= (\beta^* \alpha e^{i\omega t} + \alpha^* \beta e^{-i\omega t}) \sqrt{\frac{\hbar}{2m\omega}} \end{aligned}$$

$$\text{Let } \alpha = |\alpha| e^{i\delta}, \quad \beta = |\beta| e^{i\gamma}, \quad \delta - \gamma = \theta$$

$$\langle X(t) \rangle = \sqrt{\frac{2\hbar}{m\omega}} \cos(\omega t + \theta) |\alpha| |\beta|$$

$$\langle P_x(t) \rangle = i \sqrt{\frac{m\hbar\omega}{2}} (\beta^* \alpha e^{i\omega t} - \alpha^* \beta e^{-i\omega t})$$

$$\langle P_x(t) \rangle = -\sqrt{2m\hbar\omega} \sin(\omega t + \theta) |\alpha| |\beta|$$

$$c) \quad \hat{X}^2(t) = \frac{\hbar}{2m\omega} (a^\dagger(t))^2 + (a(t))^2 + a^\dagger(t)a(t) + a(t)a^\dagger(t)$$

$$a(t)a^\dagger(t) = a^\dagger(t)a(t) + 1 \quad [a(t), a^\dagger(t)] = 1$$

$$\begin{aligned} \langle \psi | \hat{X}^2(t) | \psi \rangle &= \frac{\hbar}{2m\omega} (|\alpha|^2 \langle 0| 2a^\dagger a + |1\rangle \langle 0| + |\beta|^2 \langle 1| 2a^\dagger a + |1\rangle \langle 1|) \\ &= \frac{\hbar}{2m\omega} (|\alpha|^2 + 3|\beta|^2) = \langle X^2(t) \rangle \end{aligned}$$

$$\hat{P}_x^2(t) = -\frac{m\hbar\omega}{2} (a^\dagger(t))^2 + (a(t))^2 - a^\dagger(t)a(t) - a(t)a^\dagger(t)$$

$$\langle \psi | \hat{p}_x^2 | \psi \rangle = \frac{m\hbar\omega}{2} \langle \psi | 2a^\dagger a + 1 | \psi \rangle$$

$$= \frac{m\hbar\omega}{2} (|\alpha|^2 + 3|\beta|^2)$$

$$\langle \Delta x^2 \rangle = \langle x^2(t) \rangle - \langle x(t) \rangle^2$$

$$= \frac{\hbar}{2m\omega} (|\alpha|^2 + 3|\beta|^2 - 4|\alpha|^2|\beta|^2 \cos^2(\omega t + \theta)) > 0$$

$$\langle \Delta p_x^2 \rangle = \langle p_x^2(t) \rangle - \langle p_x(t) \rangle^2$$

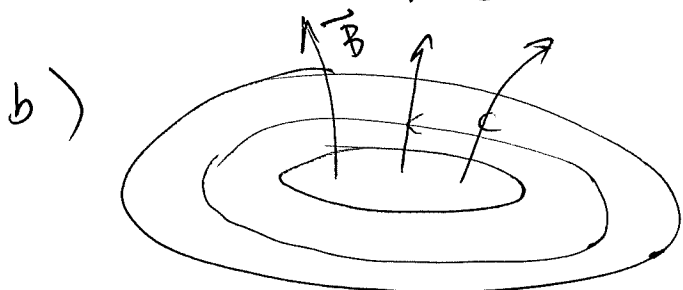
$$= \frac{m\hbar\omega}{2} (|\alpha|^2 + 3|\beta|^2 - 4|\alpha|^2|\beta|^2 \sin^2(\omega t + \theta)) > 0$$

$$3) a) \vec{V} = \frac{1}{m} \left(\vec{p} - \frac{e}{c} \vec{A} \right), \quad \vec{p} = \frac{\hbar}{i} \nabla$$

$$\vec{J}_e = \frac{q}{m} \text{Re} \left\{ \sqrt{n_s} e^{-i\theta} \left(\frac{\hbar}{i} \nabla - \frac{e}{c} \vec{A} \right) \sqrt{n_s} e^{i\theta(\vec{r})} \right\}$$

$$= \frac{n_s q}{m} \left(\hbar \nabla \theta - \frac{e}{c} \vec{A} \right)$$

$$\nabla \times \vec{J}_e = -\frac{n_s q^2}{m c} \nabla \times \vec{A} = -\frac{n_s q^2}{m c} \vec{B} \quad \checkmark$$



$\vec{J}_e = 0$ and $\vec{B} = 0$
along C.

$$0 = \frac{n_s e}{m} \left(\hbar \nabla \theta - \frac{e}{c} \vec{A} \right) \quad \text{along } C$$

$$\nabla \theta = \frac{e}{\hbar c} \vec{A} \quad \text{along } C$$

$$\oint_C \nabla \theta \cdot d\vec{l} = \frac{e}{\hbar c} \oint_C \vec{A} \cdot d\vec{l} = \frac{e}{\hbar c} \Phi$$

\parallel
 $2\pi s, \quad s \in \mathbb{Z}$ because ψ is single-valued.

$$2\pi s = \frac{e}{\hbar c} \Phi$$

$$\Phi = \frac{2\pi \hbar c}{e} s = \frac{\hbar c}{2e} s = \phi_0^{sc} s$$

$$\phi_0^{sc} = \frac{\hbar c}{2e}$$